#### Scalable Algorithms for Tensor Computations

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# Laboratory for Parallel Numerical Algorithms

Recent/ongoing research topics

- parallel matrix computations
  - QR factorization
  - triangular solve
  - eigenvalue problems
- tensor computations
  - tensor decomposition
  - sparse tensor kernels
  - tensor completion

#### simulation of quantum systems

- tensor networks
- quantum chemistry
- quantum circuits
- fast bilinear algorithms
  - convolution algorithms
  - tensor symmetry
  - fast matrix multiplication



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# Outline

#### Introduction

#### 2 Cyclops



#### 4 Tensor Networks

5 Fast Bilinear Algorithms



#### Library for Massively-Parallel Tensor Computations

Cyclops Tensor Framework<sup>1</sup> sparse/dense generalized tensor algebra

- $\bullet\,$  Cyclops is a C++ library that distributes each tensor over MPI
- Used in chemistry (PySCF, QChem)<sup>2</sup>, quantum circuit simulation (IBM/LLNL)<sup>3</sup>, and graph analysis (betweenness centrality)<sup>4</sup>
- Summations and contractions specified via Einstein notation
  E["aixbjy"] += X["aixbjy"]-U["abu"]\*V["iju"]\*W["xyu"]
- Best distributed contraction algorithm selected at runtime via models
- Support for Python (numpy.ndarray backend), OpenMP, and GPU
- Simple interface to core ScaLAPACK matrix factorization routines

<sup>&</sup>lt;sup>1</sup>https://github.com/cyclops-community/ctf

<sup>&</sup>lt;sup>2</sup>E.S., D. Matthews, J. Hammond, J.F. Stanton, J. Demmel, JPDC 2014

E. Pednault, J.A. Gunnels, G. Nannicini, L. Horesh, T. Magerlein, E. S., E. Draeger, E. Holland, and R. Wisnieff, 2017
 E.S., M. Besta, F. Vella, T. Hoefler, SC 2017

# Sparsity in Tensor Contractions



- Cyclops supports sparse representation of tensors<sup>1</sup>
- Choice of representation specified in tensor constructor
- CSR or DCSR<sup>2</sup> (2-index CSF<sup>3</sup>) representation used locally for contractions

<sup>&</sup>lt;sup>1</sup>E.S., T. Hoefler 2015

<sup>&</sup>lt;sup>2</sup>A. Bulúc, J.R. Gilbert, 2008

<sup>&</sup>lt;sup>3</sup>S. Smith, G. Karypis 2015

# All-at-Once Multi-Tensor Contraction



With sparsity, all-at-once contraction<sup>1</sup> of multiple tensors can be faster<sup>2</sup>.

• Sparse CP decomposition methods dominated in cost by MTTKRP

$$u_{ir} = \sum_{j,k} t_{ijk} v_{jr} w_{kr}$$

• All-at-once sparse MTTKRP needs less communication than pairwise

Algorithms for Tensor Computations

 $r_{ijk} = \sum_{r} t_{ijk} u_{ir} v_{jr} w_{kr}$ 

and CP tensor completion

• Cost and memory footprint reduced asymptotically

• Tensor times tensor product (TTTP) enables sparse residual

<sup>&</sup>lt;sup>1</sup>S. Smith, J. Park, G. Karypis, 2018

<sup>&</sup>lt;sup>2</sup>Zecheng Zhang, Xiaoxiao Wu, Naijing Zhang, Siyuan Zhang, and E.S. arXiv:1910.02371

# CP Tensor Decomposition Algorithms

- Tensor of order N has N modes and dimensions  $s \times \cdots \times s$
- CP and Tucker tensor decompositions<sup>1</sup>



- Alternating least squares (ALS) is most widely used method
  - Optimize one factor matrix at a time, yielding quadratic optimization subproblems
  - Achieves monotonic linear convergence
- Gauss-Newton method is an emerging alternative
  - Optimizes all factor matrices at once by quadratic approximation of nonlinear objective function
  - Non-monotonic, but can achieve quadratic convergence

<sup>1</sup>Kolda and Bader, SIAM Review 2009

# Pairwise Perturbation Algorithm



New algorithm: pairwise perturbation  $(PP)^1$  approximates ALS

- based on perturbative expansion of ALS update to approximate MTTKRP
- approximation is accurate when ALS updates stagnate
- rank  $R < s^{N-1}$  CP decomposition:
  - ALS sweep cost  $O(s^N R) \Rightarrow O(s^2 R)$ , up to 33x speed-up





Linjian Ma

#### Parallel Pairwise Perturbation Algorithm



Effective parallelization by decomposing MTTKRP into local MTTKRPs <sup>1</sup>

$$oldsymbol{U} = \mathsf{MTTKRP}(oldsymbol{\mathcal{T}},oldsymbol{V},oldsymbol{W}) \Rightarrow oldsymbol{U}_i = \sum_{j,k}\mathsf{MTTKRP}(oldsymbol{\mathcal{T}}_{ijk},oldsymbol{V}_j,oldsymbol{W}_k)$$

• processor (i,j,k) owns  $oldsymbol{\mathcal{T}}_{ijk}$ ,  $oldsymbol{V}_{j}$ , and  $oldsymbol{W}_{k}$ 

- pairwise perturbation can be used to approximate local MTTKRPs
- multi-sweep dimension-tree (MSDT) amortizes terms across sweeps

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<sup>&</sup>lt;sup>1</sup>Linjian Ma, E.S. IPDPS 2021

## Regularization and Parallelism for Gauss-Newton



New regularization scheme<sup>1</sup> for Gauss-Newton CP with implicit CG<sup>2</sup>

- Oscillates regularization parameter geometrically between lower and upper thresholds
- Achieves higher convergence likelihood
- More accurate than ALS in applications
- Faster than ALS sequentially and in parallel

<sup>2</sup>P. Tichavsky, A. H. Phan, and A. Cichocki., 2013



Navjot Singh

<sup>&</sup>lt;sup>1</sup>Navjot Singh, Linjian Ma, Hongru Yang, and E.S. arXiv:1910.12331

#### Sparse Tensor Decomposition

• MTTKRP is the most costly operation in spars CP-ALS

$$u_{ir} = \sum_{j,k} t_{ijk} v_{jr} w_{kr}$$

 Sparse MTTKRP can be done faster all-at-once than by contracting two tensors at a time



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#### Algorithms for Tensor Computations

#### Randomized Methods for Sparse Tensor Decomposition

- When seeking a low-rank R = O(1) decomposition for a sparse tensor, sketching schemes have been shown to be efficient
- In this regime, Tucker can be used to construct a CP decomposition
- Leverage score sampling on the rank-constrained least squares problem  $\min_{\mathbf{X}, \operatorname{rank}(\mathbf{X}) \leq R} \| \mathbf{A}\mathbf{X} \mathbf{B} \|_F$  leads to a state-of-the-art cost-accuracy trade-off<sup>1</sup> in approximations to Tucker-ALS
- Ideas similar to work by Liu and Moitra (2020) on tensor completion

| Algorithm for Tucker        | LS solve cost  | Sample size $(m)$   |
|-----------------------------|--|---|
| ALS                         | $O(\operatorname{nnz}(\boldsymbol{\mathcal{T}})R^{N-1})$ | /   |
| $ALS + TensorSketch^2$      | $\tilde{O}(mR^N + msR)$                                  | $O(R^{2(N-1)} \cdot 3^{N-1}/(\epsilon^2 \delta))$         |
| $ALS + TTMTS^2$             | $\tilde{O}(msR^{N-1})$                                   | $O(R^{2(N-1)} \cdot 3^{N-1} / (\epsilon^2 \delta))$       |
| $ALS + TensorSketch^1$      | $\tilde{O}(mR^{2N-2} + sR^{N-1})$                        | $O((R^{(N-1)} + 1/\epsilon^2) \cdot (3R)^{(N-1)}/\delta)$ |
| $ALS + Ieverage \ scores^1$ | $\tilde{O}(mR^{2N-2} + sR^{N-1})$                        | $O(R^{(N-1)}/(\epsilon^2\delta))$                         |

<sup>&</sup>lt;sup>1</sup>Linjian Ma and E.S., in preparation

<sup>&</sup>lt;sup>2</sup>O. Malik and S. Becker, 2018 (assuming unconstrained LSQ)

## **Tensor Completion**



- Via the CTF Python interface, we have implemented SGD, CCD, ALS (with iterative and direct solves), and Gauss-Newton<sup>1</sup>
- Can also handle a variety of loss functions (generalized decomposition)
- All-at-once primitives for MTTKRP, TTTP, and explicit solves in completion ALS drastically improve performance

<sup>&</sup>lt;sup>1</sup>Navjot Singh, Zecheng Zhang, Xiaoxiao Wu, Naijing Zhang, Siyuan Zhang, and Edgar Solomonik arXiv:1910.02371

## Quantum Circuit Simulation with Tensor Networks

• A quantum circuit is a direct description of a tensor network<sup>1</sup>



• Why use HPC to (approximately) simulate quantum circuits?

- enable development/testing/tuning of larger quantum circuits
- understand approximability of different quantum algorithms
- quantify sensitivity of algorithms to noise/error
- potentially enable new hybrid quantum-classical algorithms
- Cyclops utilized to simulate 49-qubit circuits by IBM+LLNL team via direct contraction<sup>2</sup> and by another team from via exact PEPS evolution/contraction<sup>3</sup>
- <sup>1</sup>Markov and Shi SIAM JC 2007
- <sup>2</sup>Pednault et al. arXiv:1710.05867
- <sup>3</sup>Guo et al. Phys Rev Letters, 2019

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#### Tensor Network State Simulation





# **PEPS** Contraction

- Exact contraction of PEPS is #P-complete, so known methods have exponential cost in the number of sites
- PEPS contraction is needed to compute expectation values
- Boundary contraction is common for finite PEPS and can be simplified with einsumsvd



#### Implicit Randomized einsumsvd

• The einsumsvd primitive provides an effective abstraction for tensor network simulation methods



 An efficient general implementation is to leverage randomized SVD / orthogonal iteration, which iteratively computes a low-rank SVD by a matrix-matrix product that can be done implicitly via tensor contractions

# PEPS Benchmark Performance



- We introduce a new library, Koala<sup>1</sup>, for high-performance simulation of quantum circuits and time evolution with PEPS<sup>2</sup>
- Koala achieves good parallel scalability for approximate gate application (evolution) and contraction
- Approximation can be effective even for adversarially-designed circuits such as Google's random quantum circuit model (figure on right)

<sup>2</sup>Yuchen Pang, Tianyi Hao, Annika Dugad, Yiqing Zhou, and E.S. SC 2020

<sup>&</sup>lt;sup>1</sup>https://github.com/cyclops-community/koala

# PEPS Accuracy for Quantum Simulation



- ITE code achieves improvable accuracy with increased PEPS bond dimension, but approximation in PEPS contraction is not variational
- Variational quantum eigensolver (VQE), which represents a wavefunction using a parameterized circuit  $U(\theta)$  and minimizes

#### $\left< U(\theta) \right| H \left| U(\theta) \right>,$

also achieves improvable accuracy with higher PEPS bond dimension

#### Automatic Differentiation for Tensor Computations

• Tensor network and tensor decomposition methods all typically based on applying Newton's method on a sequence of subsets of variables



- Automatic differentiation (AD) in principle enables automatic generation of these methods
- However, existing AD tools such as Jax (used by TensorFlow) are designed for deep learning and are ineffective for more complex tensor computations
  - these focus purely on first order optimization via Jacobian-vector products
  - unable to propagate tensor algebra identities such as  $(A \otimes B)^{-1} = A^{-1} \otimes B^{-1}$  to generate efficient code

# AutoHOOT: Automatic High-Order Optimization for Tensors

- AutoHOOT<sup>1</sup> provides a tensor-algebra centric AD engine
- Designed for einsum expressions and alternating minimization common in tensor decomposition and tensor network methods
- Python-level AD is coupled with optimization of contraction order and caching of intermediates
- Generates code for CPU/GPU/supercomputers using high-level back-end interface to tensor contractions



## Group Symmetry in Tensor Contractions

• Tensor with cyclic group symmetry can be represented as block-sparse

 $t_{ijk\dots} = 0$  if  $\lfloor i/G_1 \rfloor + \lfloor j/G_2 \rfloor + \lfloor k/G_3 \rfloor + \dots \neq 0 \pmod{G}$ .

- Group symmetries of multiple types arise due to conservation laws when physical systems (quantum number symmetry, spin symmetry, rotational symmetry, translational symmetry)
- New contraction algorithm, *irreducible representation alignment* uses new dense reduced form tensor to handle group symmetry without looping over blocks or sparsity<sup>1</sup>



<sup>1</sup>Y. Gao, P. Helms, G. Chan, and E.S., arXiv:2007.08056

# Permutational Symmetry in Tensor Contractions



New contraction algorithms reduce cost via permutational symmetry<sup>1</sup>

- Symmetry is hard to use in contraction e.g.  $m{y}=Am{x}$  with A symmetric
- For contraction of order s + v and v + t tensors to produce an order s + t tensor, previously known approaches reduce cost by s!t!v!
- New algorithm reduces number of *products* by  $\omega$ ! where  $\omega = s + t + v$ , leads to same reduction in *cost* for partially-symmetric contractions

$$\boldsymbol{C} = \boldsymbol{A}\boldsymbol{B} + \boldsymbol{B}\boldsymbol{A} \Rightarrow c_{ij} = \sum_{k} [(a_{ij} + a_{ik} + a_{jk}) \cdot (b_{ij} + b_{ik} + b_{jk})] - \dots$$

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<sup>&</sup>lt;sup>1</sup>E.S, J. Demmel, CMAM 2020

#### Communication Cost of Fast Bilinear Algorithms

• Given inputs a and b, a bilinear algorithm computes

$$\boldsymbol{c} = \boldsymbol{F}^{(\boldsymbol{C})}[(\boldsymbol{F}^{(\boldsymbol{A})T}\boldsymbol{a}) \circ (\boldsymbol{F}^{(\boldsymbol{B})T}\boldsymbol{b})]$$

- All fast algorithmns for matrix multiplication, convolution, and symmetric tensor contractions are bilinear algorithms
- Communication lower bounds can be attained for any execution of a bilinear algorithm, given a lower bound on the rank of subset of columns of  $F^{(A)}$ ,  $F^{(B)}$ , or  $F^{(C)1}$
- Can automatically obtain rank lower bounds for  $A \otimes B$  from that of A and B, enabling application of these lower bounds to nested algorithms such Strassen's algorithm, convolution, and symmetry preserving algorithms applied to partially symmetric contractions<sup>2</sup>

<sup>2</sup>Caleb Ju, Yifan Zhang, E.S. in preparation

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<sup>&</sup>lt;sup>1</sup>E.S., J. Demmel, T. Hoefler arXiv:1707.04618

### Conclusion and Future Directions

- Talk introduced new algorithms and software for tensor contractions, tensor decomposition, and tensor networks, considering challenges involved in handling symmety, sparsity, and parallelism
- We are also exploring solvers for QP interior point methods via a new Schur complementation strategy and preconditioners<sup>1</sup>



#### <sup>1</sup>Samah Karim and E.S. in preparation

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Algorithms for Tensor Computations

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